STA 331 2.0 Stochastic Processes

2. Markov Chains

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n-step transition probabilities - P_{iii}^n

 P_{ij} - One step transition probabilities

$$P_{ij}^n$$
 - n - step transition probabilities

Probability that a process in state i will be in state j after n additional transitions. That is,

$$P_{ij}^n = P(X_{n+k} = j | X_k = i), \ n \ge 0, \ i, j \ge 0.$$

Chapman-Kolmogrov Equations

$$\mathcal{P}_{ij}^{n+m}=\sum_{k=0}^{\infty}\mathcal{P}_{ik}^{n}\mathcal{P}_{kj}^{m}$$
 for all n, m \geq 0, all i, j,

where, $P_{ik}^n P_{kj}^m$ represents the probability that starting in *i* the process will go to state *j* in n + m with an intermediate stop in state *k* after *n* steps.

In-class

This can be used to compute *n*-step transition probabilities

In-class

 $P_{ij}^{n+m} = \sum_{k=0}^{\infty} P_{ik}^n P_{kj}^m$ for all n, m \geq 0, all i, j. Proof:

The n-step transition matrix is

n - step transition matrix (cont.)

The Chapman-Kolmogrov equations imply

$$\mathbf{P}^{(n+m)}=P^{(n)}P^{(m)}.$$

In particular,

$$\mathbf{P}^{(2)} = \mathbf{P}^{(1)}\mathbf{P}^{(1)} = \mathbf{P}\mathbf{P} = \mathbf{P}^2.$$

By induction,

$$\mathbf{P}^{(n)} = \mathbf{P}^{(n-1+1)} = \mathbf{P}^{n-1}\mathbf{P} = \mathbf{P}^n.$$

Proposition

$$P^{(n)} = P^n = P \times P \times P \times ... \times P, \ n \ge 1.$$

That is, $P^{(n)}$ is equal to P multiplied by itself n times.

Example 1

Let $X_i = 0$ if it rains on day *i*; otherwise $X_i = 1$. Suppose $P_{00} = 0.7$ and $P_{10} = 0.4$. Suppose it rains on Monday. Then, what is the probability that it rains on Friday.

p <- matrix(c(0.7, 0.4, 0.3, 0.6), nrow = 2); p

[,1] [,2] [1,] 0.7 0.3 [2,] 0.4 0.6

p%*%p%*%p%*%p

[,1] [,2] [1,] 0.5749 0.4251 [2,] 0.5668 0.4332 So that $P_{00}^{(4)} = 0.5749$ Recall the example from class in which the weather today depends on the weather for the previous two days.

						0.7	0	0.3	0	
Sate	Yesterday	Today	Tomorrow	Probability		~ -	~	~ -	~	l
0-RR	1	1	1	0.7	-	0.5	0	0.5	0	l
1-SR	0	1	1	0.5	$\mathbf{P} = $					l
2-RS	1	0	1	0.4		0	0.4	0	0.6	
3-SS	0	0	1	0.2						
						0	0.2	0	0.8	l
							-	-		L

Now suppose that it was sunny both yesterday and the day before yesterday. What's the probability that it will rain tomorrow?

[,1] [,2] [,3] [,4] [1,] 0.49 0.12 0.21 0.18 [2,] 0.35 0.20 0.15 0.30 [3,] 0.20 0.12 0.20 0.48 [4,] 0.10 0.16 0.10 0.64

Unconditional Probabilities

Suppose we know the initial probabilities,

$$\alpha_i = P(X_0 = i)$$
, , $i = 0, 1, 2, ...$

and $\sum_i \alpha_i = 1$.

According to the Law of total probability

$$P(X_n = j) = \sum_{i=0}^{\infty} P(X_n = j \cap X_0 = i)$$
$$= \sum_{i=0}^{\infty} P(X_n = j | X_0 = i) P(X_0 = i)$$
$$= \sum_{i=0}^{\infty} P_{ij}^{(n)} \alpha_i$$

Example 3 (based on Example 1)

Let $X_i = 0$ if it rains on day *i*; otherwise $X_i = 1$. Suppose $P_{00} = 0.7$ and $P_{10} = 0.4$. Suppose it rains on Monday. Suppose $P(X_0 = 0) = 0.4$ and $P(X_0 = 1) = 0.6$. What is the probability that it will not rain on the 4th day after we start keeping records?

Example 3 (cont.)

Let $X_i = 0$ if it rains on day *i*; otherwise $X_i = 1$. Suppose $P_{00} = 0.7$ and $P_{01} = 0.4$. Suppose it rains on Monday. Suppose $P(X_0 = 0) = 0.4$ and $P(X_0 = 1) = 0.6$. What is the probability that it will not rain on the 4th day after we start keeping records?

p <- matrix(c(0.7, 0.4, 0.3, 0.6), nrow = 2)
p%*%p%*%p%*%p</pre>

[,1] [,2] [1,] 0.5749 0.4251 [2,] 0.5668 0.4332

Example 4

Suppose that a taxi driver operates between Wijerama and Nugegoda. If the driver is in Wijerama the probability that he gets a trip to Nugegoda from one passenger or a group of travelling together is 0.2 and that for him to get a trip nearby Wijerama is 0.8. If the driver is in Nugegoda he has equal chance of getting a trip to Wijerama or nearby Nugegoda. The behaviour of the driver evolves over time in a probabilistic manner.

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0 - Wijerama, 1 - Nugegoda

\mathbf{P} = \begin{bmatrix} 0.8 & 0.2\\ 0.5 & 0.5 \end{bmatrix}
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Example 4 (cont.)

 i) If the driver is currently at Wijerama, what is the probability that he will be back at Wijerama after three trips?

Example 4 (cont.)

 i) If the driver is currently at Wijerama, what is the probability that he will be back at Wijerama after three trips?

p <- matrix(c(0.8, 0.5, 0.2, 0.5), ncol=2)
p%*%p%*%p</pre>

[,1] [,2] [1,] 0.722 0.278 [2,] 0.695 0.305

Example 4 (cont.)

 ii) If the driver is at Nugegoda, how many trips on the average will be in Nugegoda before he next goes to Wijerama?

Example 4 (cont.): In-class

Suppose $P^{(0)} = (0.5, 0.5)$, equal chance for driver be in either Wijerama or Nugegoda. What is the probability he will be in Wijerama after the first trip. *In-class: Method 1*

Probability after n-th step

$$\mathbf{P}^{(n)} = \mathbf{P}^{(0)}\mathbf{P}^n$$

In-class: Method 2

Types of States

Definition: If $P_{ij}^{(n)} > 0$ for some $n \ge 0$, state *j* is **accessible** from *i*.

Notation: $i \rightarrow j$.

Definition: If $i \rightarrow j$ and $j \rightarrow i$, then *i* and *j* communicate. Notation: $i \leftrightarrow j$. Communication is an equivalence relation:

- (i) $i \leftrightarrow i$ for all *i* (reflexive).
- (ii) $i \leftrightarrow j$ implies $j \leftrightarrow i$ (symmetric).
- (iii) $i \leftrightarrow j$ and $j \leftrightarrow k$ imply $i \leftrightarrow k$ (transitive).

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(iii) $i \leftrightarrow j$ and $j \leftrightarrow k$ imply $i \leftrightarrow k$ (transitive).

Note:

- Two states that communicate are said to be in the same **class**.
- The concept of communication divides the state space up into a number of separate classes.

In-class: demonstration

Definition: An equivalence class consists of all states that communicate with each other.

Remark: Easy to see that two equivalence classes are disjoint. Example: The following P has equivalence classes $\{0, 1\}$ and $\{2, 3\}$

	0.5	0.5	0	0]
D _	0.5	0.5	0	0
F =	0	0	0.75	0.25
	0	0	0.25	0.75

What about this?

$$\mathbf{P} = \begin{bmatrix} 0.5 & 0.5 & 0 & 0 \\ 0.5 & 0.3 & 0.2 & 0 \\ 0 & 0 & 0.75 & 0.25 \\ 0 & 0 & 0.25 & 0.75 \end{bmatrix}$$

Definition: A MC is irreducible if there is only one equivalence class (i.e., if all states communicate with each other).

What about these?

$$\mathbf{P} = \begin{bmatrix} 0.5 & 0.5 & 0 & 0 \\ 0.5 & 0.5 & 0 & 0 \\ 0 & 0 & 0.75 & 0.25 \\ 0 & 0 & 0.25 & 0.75 \end{bmatrix} \qquad \mathbf{P} = \begin{bmatrix} 0.5 & 0.5 & 0 & 0 \\ 0.5 & 0.3 & 0.2 & 0 \\ 0 & 0 & 0.75 & 0.25 \\ 0 & 0 & 0.25 & 0.75 \end{bmatrix}$$

What about these?

$$\mathbf{P} = \left[\begin{array}{cc} 0.5 & 0.5 \\ 0.25 & 0.75 \end{array} \right]$$

$$\mathbf{P} = \begin{bmatrix} 0.25 & 0 & 0.75 \\ 1 & 0 & 0 \\ 0 & 0.5 & 0.5 \end{bmatrix}$$

Consider a Markov chain with a state space $S = \{0, 1, 2, 3, 4\}$ and having the following one-step transition probability matrix.

$$\mathbf{P} = \begin{bmatrix} 0.4 & 0.2 & 0 & 0.4 & 0 \\ 0.2 & 0.4 & 0.1 & 0.3 & 0 \\ 0.1 & 0.2 & 0.5 & 0.1 & 0.1 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Example 4.10

Example 4.11

Example 4.12

¹Introduction to Probability Models, Sheldon M. Ross

Reading Section 4.3: Classification of States²

²Introduction to Probability Models, Sheldon M. Ross